Hebbian Learning and Spiking Neurons

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A correlation-based ("Hebbian") learning rule at a spike level with millisecond resolution is formulated, mathematically analyzed, and compared with learning in a firing-rate description. The relative timing of pre- and postsynaptic spikes influences synaptic weights via an asymmetric "learning window". A differential equation for the learning dynamics is derived under the assumption that the time scales of learning and neuronal spike dynamics can be separated. The differential equation is solved for a Poissonian neuron model with stochastic spike arrival. It is shown that correlations between input and output spikes tend to stabilize structure formation. With an appropriate choice of parameters, learning leads to an intrinsic normalization of the average weight and the output firing rate. Noise generates diffusion-like spreading of synaptic weights.

On a time scale of 1 ms, however, neuronal activity consists of a sequence of short electrical pulses, the so-called action potentials or spikes. During recent years experimental and theoretical evidence has accumulated which suggests that temporal coincidences between spikes on a millisecond or even sub-millisecond scale play an important role in neuronal information processing [13–24]. If so, a rate description may, and often will, neglect important information that is contained in the temporal structure of a neuronal spike train.

Neurophysiological experiments also suggest that the change of a synaptic efficacy depends on the precise timing of postsynaptic action potentials with respect to presynaptic input spikes on a time scale of 10 ms. Specifically, a synaptic weight is found to increase if presynaptic firing precedes a postsynaptic spike, and to decrease otherwise [25, 26]; see also [27–33]. Our description of learning at a temporal resolution of spikes takes these effects into account.

In contrast to the standard rate models of Hebbian learning, we introduce and analyze a learning rule where synaptic modifications are driven by the temporal correlations between pre- and postsynaptic spikes. First steps towards a detailed modeling of temporal relations have been taken for rate models in [34] and for spike models in [22,35–43].

II. DERIVATION OF THE LEARNING EQUATION

A. Specification of the Hebb Rule

We consider a neuron that receives input from \( N \geq 1 \) synapses with efficacies \( J_i, \ 1 \leq i \leq N; \) cf. Fig 1. We assume that changes of \( J_i \) are induced by pre- and postsynaptic spikes. The learning rule consists of three parts. (i) Let \( t_f^j \) be the arrival time of the \( f \)th input spike at synapse \( i \). The arrival of a spike induces the weight \( J_i \) to change by an amount \( \eta w^{\text{in}} \) which can be either positive

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or negative. The quantity $\eta > 0$ is a “small” parameter.

(ii) Let $t^n$ be the $n$th output spike of the neuron under consideration. This event triggers the change of all $N$ efficacies by an amount $\eta w^{\text{out}}$, which can also be positive or negative. (iii) Finally, time differences between all pairs of input and output spikes influences the change of the efficacies. Given a time difference $s = t^n - t^n$ between input and output spike, $J_i$ is changed by an amount $\eta W(s)$ where the learning window $W$ is a real-valued function. It is to be specified shortly; cf. also Fig. 6.

![Diagram](image)

**FIG. 1.** Single neuron. We study the development of synaptic weights $J_i$ (small filled circles, $1 \leq i \leq N$) of a single neuron (large circle). The neuron receives input spike trains denoted by $S_i^{\text{in}}$ and produces output spike trains denoted by $S_i^{\text{out}}$.

Starting at time $t$ with an efficacy $J_i(t)$, the total change $\Delta J_i(t) = J_i(t + \mathcal{T}) - J_i(t)$ in a time interval $\mathcal{T}$, which may be interpreted as the length of a learning trial, is calculated by summing the contributions of input and output spikes as well as all pairs of input and output spikes occurring in the time interval $[t, t + \mathcal{T}]$. Denoting the input spike train at synapse $i$ by a series of $\delta$ functions, $S_i^{\text{in}}(t) = \sum_j \delta(t - t^j_i)$, and, similarly, output spikes by $S_i^{\text{out}}(t) = \sum_j \delta(t - t^j_i)$, we can formulate the rules (i)--(iii) explicitly by putting

$$
\Delta J_i(t) = \eta \int_t^{t+\mathcal{T}} dt' \left[ w^{\text{in}} S_i^{\text{in}}(t') + w^{\text{out}} S_i^{\text{out}}(t') \right]
$$

$$
+ \eta \int_t^{t+\mathcal{T}} dt' \int_t^{t+\mathcal{T}} dt'' W(t'' - t') S_i^{\text{in}}(t'') S_i^{\text{out}}(t')
$$

$$
= \left[ \sum_{t^j_i} w^{\text{in}} + \sum_{t^j_i} w^{\text{out}} + \sum_{t^j_i} W(t^j_i - t^n) \right].
$$

In (1b) the prime denotes that only firing times $t^j_i$ and $t^n$ in the time interval $[t, t+\mathcal{T}]$ are to be taken into account; cf. Fig. 2.

![Diagram](image)

**FIG. 2.** Hebbian learning and spiking neurons - schematic. In the bottom graph we plot the time course of the synaptic weight $J_i(t)$ evoked through input and output spikes (upper graphs, vertical bars). An output spike, e.g., at time $t^a$, induces the weight $J_i$ to change by an amount $w^{\text{out}}$ which is negative here. To consider the effect of correlations between input and output spikes, we plot the learning window $W(s)$ (center graphs) around each output spike, where $s = 0$ matches the output spike times (vertical dashed lines). The three input spikes at times $t^j_i$, $t^j_i$, and $t^j_i$ (vertical dotted lines) increase $J_i$ by an amount $w^{\text{in}}$ each. There is no influence of correlations between these input spikes and the output spike at time $t^a$. This becomes visible with the aid of the learning window centered at $t^a$. The input spikes are too far away in time. The next output spike at $t^b$, however, is close enough to the previous input spike at $t^b$. The weight $J_i$ is changed by $w^{\text{out}} < 0$ plus the contribution $W(t^b - t^a) > 0$, the sum of which is positive (arrowheads). Similarly, the input spike at time $t^c$ leads to a change $w^{\text{in}} + W(t^c - t^b) < 0$.

Equation (1) represents a Hebb-type learning rule since they correlate pre- and postsynaptic behavior. More precisely, here our learning scheme depends on the time sequence of input and output spikes. The parameters $w^{\text{in}}, w^{\text{out}}$ as well as the amplitude of the learning window $W$ may, and in general will, depend on the value of the efficacy $J_i$. Such a $J_i$ dependence is useful so as to avoid unbounded growth of synaptic weights. Even though we have not emphasized this in our notation, most of the theory developed below is valid for $J_i$-dependent parameters; cf. Sec. VB.

### B. Ensemble Average

Given that input spiking is random but partially correlated and that the generation of spikes is in general a complicated dynamic process, an analysis of (1) is formidable. We therefore simplify it. We have introduced a small parameter $\eta > 0$ into (1) with the idea in mind that the learning process is performed on a much slower time scale than the neuronal dynamics. Thus we expect that only averaged quantities enter the learning dynamics.

Considering averaged quantities may also be useful in order to disregard the influence of noise. In (1) spikes
are discrete events that trigger a discontinuous change of the synaptic weight; cf. Fig. 2 (bottom). If we assume a stochastic spike arrival or if we assume a stochastic process for generating output spikes, the change $\Delta J_i$ is a random variable, which exhibits fluctuations around some mean drift. Averaging implies that we focus on the drift and calculate the expected rate of change. Fluctuations are treated in Sec. VI.

1. Self-Averaging of Learning

Effective learning needs repetition over many trials of length $T$, each individual trial being independent of the previous ones. Equation (1) tells us that the result of the individual trials are to be summed. According to the (strong) law of large numbers [44] in conjunction with $\eta$ being “small” [45] we can average the resulting equation, viz., (1), whatever the random process. In other words, the learning procedure is self-averaging. Instead of averaging over several trials we may also consider one single long trial during which input and output characteristics remain constant. Again, if $\eta$ is sufficiently small, time scales are separated and learning is self-averaging.

The corresponding average over the resulting random process is denoted by angular brackets $\langle \ldots \rangle$ and called an ensemble average, in agreement with physical usage. It is a probability measure on a probability space, which need not be specified explicitly. We simply refer to the literature [44]. Substituting $s = t' - t$ on the right-hand side of (1a), dividing both sides by $T$ we obtain

$$\frac{\langle \Delta J_i(t) \rangle}{T} = \frac{\eta}{T} \int_{t}^{t + T} dt' \left[ u^{\text{in}} (\langle S_{i}^{\text{in}}(t') \rangle + w^{\text{out}} \langle S_{i}^{\text{out}}(t') \rangle) \right] \quad (2)$$

$$+ \frac{\eta}{T} \int_{t}^{t + T} dt' \int_{t - t'}^{t + T - t'} ds \ W(s) \langle S_{i}^{\text{in}}(t' + s) S_{i}^{\text{out}}(t') \rangle .$$

2. Example: Inhomogeneous Poisson Process

Averaging the learning equation before proceeding is justified if both input and output processes will be taken to be inhomogeneous Poisson processes, which will be assumed throughout Secs. IV–VI. An inhomogeneous Poisson process with time dependent rate function $\lambda_i(t) \geq 0$ is characterized by two facts: (i) disjoint intervals are independent and (ii) the probability of getting a single event at time $t$ in an interval of length $\Delta t$ is $\lambda_i(t) \Delta t$, more events having a probability $\lambda_i(t) \Delta t$; see also [46], App. A for a simple exposition of the underlying mathematics. The integrals in (1a) or the sums in (1b) therefore decompose into many independent events and thus, the strong law of large numbers applies to them. The output is a temporally local process as well so that the strong law of large numbers also applies to the output spikes at times $t^n$ in (1).

If we describe input spikes by inhomogeneous Poisson processes with intensity $\lambda_{i}^{\text{in}}(t)$, then we may identify the ensemble average over a spike train with the stochastic intensity, $\langle S_{i}^{\text{in}}(t) \rangle = \lambda_{i}^{\text{in}}(t)$; cf. Fig. 3. The intensity $\lambda_{i}^{\text{in}}(t)$ can be interpreted as the instantaneous rate of spike arrival at synapse $i$. In contrast to temporally averaged mean firing rates, the instantaneous rate may vary on a fast time scale in many biological systems; cf. Sec. III C. The stochastic intensity $\langle S_{i}^{\text{out}}(t) \rangle$ is the instantaneous rate of observing an output spike, where $\langle \ldots \rangle$ is an ensemble average over both the input and the output. Finally, the correlation function $\langle S_{i}^{\text{in}}(t') S_{i}^{\text{out}}(t'' \rangle$ is to be interpreted as the joint probability density for observing an input spike at synapse $i$ at the time $t'$ and an output spike at time $t''$. 

![Figure 3](image)

**FIG. 3.** Inhomogeneous Poisson process. In the upper graph we have plotted an example of an instantaneous rate $\lambda_{i}^{\text{in}}(t)$ in units of Hz. The average rate is 10 Hz. The lower graph shows a spike train $S_{i}^{\text{in}}(t)$ which is a realization of an inhomogeneous Poisson process with rate $\lambda_{i}^{\text{in}}(t)$. The spike times are denoted by vertical bars.

C. Separation of Time Scales

We require the length $T$ of a learning trial in (2) to be much larger than typical interspike intervals. Both many input spikes at any synapse and many output spikes should occur on average in a time interval of length $T$. Then, using the notation $\int_{t}^{T} dt' / T = T^{-1} \int_{t}^{T} dt' / T$, we may introduce the mean firing rates $\nu_{i}^{\text{in}}(t) = \langle S_{i}^{\text{in}}(t) \rangle$ and $\nu_{i}^{\text{out}}(t) = \langle S_{i}^{\text{out}}(t) \rangle$. We call $\nu_{i}^{\text{in}}$ and $\nu_{i}^{\text{out}}$ mean firing rates in order to distinguish them from the previously defined instantaneous rates $\langle S_{i}^{\text{in}} \rangle$ and $\langle S_{i}^{\text{out}} \rangle$ which are the result of an ensemble average only. Because of their definition, mean firing rates $\nu$ always vary slowly as a function of time. That is, they vary on a time scale of the order of $T$. The quantities $\nu_{i}^{\text{in}}$ and $\nu_{i}^{\text{out}}$ therefore carry hardly any information that may be present in the timing of discrete spikes.

For the sake of further simplification of (2), we define the width $W$ of the learning window $W(s)$ and consider the case $T \gg W$. Most of the “mass” of the learning window should be inside the interval $[-W, W]$. Formally we
require $\int_{\mathcal{W}} ds \, |W(s)| \gg \int_{-\infty}^{\infty} ds \, |W(s)| + \int_{\mathcal{W}} \infty ds \, |W(s)|$. For $\mathcal{T} \gg \mathcal{W}$ the integration over $s$ in (2) can be extended to run from $-\infty$ to $\infty$. With the definition of a temporally averaged correlation function,
\begin{equation}
C_i(s; t) = \langle S_i^m(t + s) S_i^{out}(t) \rangle,
\end{equation}
the last term on the right in (2) reduces to $\int_{-\infty}^{\infty} ds \, W(s) C_i(s; t)$. Correlations between presynaptic and postsynaptic spikes, thus, enter spike-based Hebbian learning through $C_i$ convolved with the window $W$. We note that the correlation $C_i(s; t)$, though being both an ensemble and a temporally averaged quantity, may change as a function of $s$ on a much faster time scale than $\mathcal{T}$ or the width $W$ of the learning window. The temporal structure of $C_i$ depends essentially on the neuron (model) under consideration. An example is given in Sec. IV A.

We require learning to be a slow process; cf. Sec. III B 1. More specifically, we require that $J$ values do not change much in the time interval $\mathcal{T}$. Thus $\mathcal{T}$ separates the time scales $\mathcal{W}$ (width of the learning window $W$) from the time scale of the learning dynamics, which is proportional to $\eta^{-1}$. Under those conditions we are allowed to approximate the left-hand side of (2) by the rate of change $dJ_i/dt$, whereby we have omitted the angular brackets for brevity. Absorbing $\eta$ into the learning parameters $w_i^{in}$, $w_i^{out}$, and $W$, we obtain
\begin{equation}
d \frac{d}{dt} J_i(t) = w_i^{in} \nu_i^{in}(t) + w_i^{out} \nu_i^{out}(t) + \int_{-\infty}^{\infty} ds \, W(s) C_i(s; t).
\end{equation}
The ensemble averaged learning equation (4), which holds for any neuron model, will be the starting point of the arguments below.

III. SPIKE-BASED AND RATE-BASED HEBBIAN LEARNING

In this section we indicate the assumptions that are required to reduce spike-based to rate-based Hebbian learning and outline the limitations of the latter.

A. Rate-Based Hebbian Learning

In neural network theory, the hypothesis of Hebb [1] is usually formulated as a learning rule where the change of a synaptic efficacy $J_i$ depends on the correlation between the mean firing rate $\nu_i^{in}$ of the $i$th presynaptic neuron and the mean firing rate $\nu_i^{out}$ of a postsynaptic neuron, viz.,
\begin{equation}
\frac{dJ_i}{dt} = J_i = a_0 + a_1 \nu_i^{in} + a_2 \nu_i^{out} + a_3 \nu_i^{in} \nu_i^{out} + a_4 (\nu_i^{in})^2 + a_5 (\nu_i^{out})^2,
\end{equation}
where $a_0 < 0$, $a_1$, $a_2$, $a_3$, $a_4$, and $a_5$ are proportionality constants. Apart from the decay term $a_0$ and the “Hebbian” term $\nu_i^{in} \nu_i^{out}$ proportional to the product of input and output rates, there are also synaptic changes which are driven separately by the pre- and postsynaptic rates. The parameters $a_0, \ldots, a_5$ may depend on $J_i$, Equation (5) is a general formulation up to second order in the rates; see, e.g., [3, 47, 12].

B. Spike-Based Hebbian Learning

To get (5) from the spike-based learning rule in (4) two approximations are required. First, if there are no correlations between input and output spikes apart from the correlations contained in the instantaneous rates, we can write $\langle S_i^{in}(t') S_i^{out}(t) \rangle \approx \langle S_i^{in}(t') \rangle \langle S_i^{out}(t) \rangle$. Second, if these rates change slowly as compared to $\mathcal{T}$, then we have $C_i(s; t) \approx \nu_i^{in}(t + s) \nu_i^{out}(t)$. In addition, $\nu(t)$ is the time evolution on a slow time scale; cf. the discussion after (3). Since we have $\mathcal{T} \gg \mathcal{W}$, the rates $\nu_i^{in}$ also change slowly as compared to the width $\mathcal{W}$ of the learning window and thus, we may replace $\nu_i^{in}(t + s)$ by $\nu_i^{in}(t)$ in the correlation term $\int_{-\infty}^{\infty} ds \, W(s) C_i(s; t)$. This yields $\int_{-\infty}^{\infty} ds \, W(s) C_i(s; t) \approx W(0) \nu_i^{in}(t) \nu_i^{out}(t)$ where $W(0) := \int_{-\infty}^{\infty} ds \, W(s)$. Under the above assumptions we can identify $W(0)$ with $a_0$. By further comparison of (4) with (5) we identify $w_i^{in}$ with $a_1$ and $w_i^{out}$ with $a_2$, and we are able to reduce (4) to (5) by setting $a_3 = a_4 = a_5 = 0$.

C. Limitations of Rate-Based Hebbian Learning

The assumptions necessary to derive (5) from (4), however, are not generally valid. According to the results of Markram et al. [25] the width $\mathcal{W}$ of the Hebbian learning window in cortical pyramidal cells is in the range of 100 ms. At retinocortical synapses $\mathcal{W}$ is also in the range of 100 ms [26].

A mean rate formulation thus requires that all changes of the activity are slow at a time scale of 100 ms. This is not necessarily the case. The existence of oscillatory activity in the cortex in the range of 40 Hz (e.g., [14, 15, 20, 48]) implies activity changes every 25 ms. Retinal ganglion cells fire synchronously at a time scale of about 10 ms [49]; cf. also [50]. Much faster activity changes are found in the auditory system. In the auditory pathway of, e.g., the barn owl, spikes can be phase-locked to frequencies of up to 8 kHz [51–53]. Furthermore, beyond the correlations between instantaneous rates additional correlations between spikes may exist.

Because of all the above reasons, the learning rule (5) in the simple rate formulation is insufficient to provide a generally valid description. In Secs. IV–V we will therefore study the full spike-based learning equation (4).
IV. STOCHASTICALLY SPIKING NEURONS

A crucial step in analyzing (4) is determining the correlations $C_i$ between input spikes at synapse $i$ and output spikes. The correlations, of course, depend strongly on the neuron model under consideration. To highlight the main points of learning we study a simple toy model. Input spikes are generated by an inhomogeneous Poisson process and fed into a stochastically firing neuron model. For this scenario we are able to derive an analytical expression for the correlations between input and output spikes. The introduction of the model and the derivation of the correlation function is the topic of the first subsection. In the second subsection we use the correlation function in the learning equation (4) and analyze the learning dynamics. In the final two subsections the relation to the work of Linsker [3] (a rate formulation of Hebbian learning) and some extensions based on spike coding are considered.

A. Poisson Input and Stochastic Neuron Model

We consider a single neuron which receives input via $N$ synapses $1 \leq i \leq N$. The input spike trains arriving at the $N$ synapses are statistically independent and generated by an inhomogeneous Poisson process with time-dependent intensities $\langle S_{in}^i(t) \rangle = \lambda_{in}^i(t)$ with $1 \leq i \leq N$ [46].

In our simple neuron model we assume that output spikes are generated stochastically with a time-dependent rate $\lambda_{out}(t)$ that depends on the timing of input spikes. Each input spike arriving at synapse $i$ at time $t_i^f$ increases (or decreases) the instantaneous firing rate $\lambda_{out}(t)$ by an amount $J_i(t_i^f) \epsilon(t - t_i^f)$, where $\epsilon$ is a response kernel. The effect of an incoming spike is thus a change in probability density proportional to $J_i$. Causality is imposed by the requirement $\epsilon(s) = 0$ for $s > 0$. In biological terms, the kernel $\epsilon$ may be identified with an excitatory (or inhibitory) postsynaptic potential. In throughout what follows, we assume excitatory couplings $J_i > 0$ for all $i$ and $\epsilon(s) \geq 0$ for all $s$. In addition, the response kernel $\epsilon(s)$ is normalized to $\int d s \epsilon(s) = 1$; cf. Fig. 4.

The contributions from all $N$ synapses as measured at the axon hillock we assume to add up linearly. The result gives rise to a linear inhomogeneous Poisson model with intensity

$$\lambda_{out}(t) = \nu_0 + \sum_{i=1}^{N} \sum_{j} J_i(t_j^f) \epsilon(t - t_j^f).$$

(6)

Here, $\nu_0$ is the spontaneous firing rate and the sums run over all spike arrival times at all synapses. By definition, the spike generation process (6) is independent of previous output spikes. In particular, this Poisson model does not include refractoriness.

In the context of (4), we are interested in ensemble averages over both the input and the output. Since (6) is a linear equation, the average can be performed directly and yields

$$\langle S_{out}^i(t) \rangle = \nu_0 + \sum_{i=1}^{N} J_i(t) \int_0^\infty ds \epsilon(s) \lambda_{in}^i(t - s).$$

(7)

In deriving (7) we have replaced $J_i(t_j^f)$ by $J_i(t)$ because efficacies are assumed to change adiabatically with respect to the width of $\epsilon$. The ensemble-averaged output rate in (7) depends on the convolution of $\epsilon$ with the input rates. In what follows we denote

$$\lambda_{in}^i(t) = \int_0^\infty ds \epsilon(s) \lambda_{in}^i(t - s).$$

(8)

Equation (7) may suggest that input and output spikes are statistically independent — which is not the case. To show this explicitly, we determine the ensemble averaged correlation $\langle S_{in}^i(t + s) \cdot S_{out}^j(t) \rangle$ in (3). Since $\langle S_{in}^i(t + s) \cdot S_{out}^j(t) \rangle$ corresponds to a joint probability, it equals the probability density $\lambda_{in}^i(t + s)$ for an input spike at synapse $i$ at time $t+s$ times the conditional probability density of observing an output spike at time $t$ given the above input spike at $t+s$,

$$\langle S_{in}^i(t + s) \cdot S_{out}^j(t) \rangle = \lambda_{in}^i(t + s) \left[ \nu_0 + J_i(t) \epsilon(-s) + \sum_{j=1}^{N} J_j(t) \lambda_{in}^j(t) \right].$$

(9)

The first term inside the square brackets is the spontaneous output rate, the second term is the specific contribution caused by the input spike at time $t+s$, which vanishes for $s > 0$. We are allowed to write $J_i(t)$ instead of the “correct” weight $J_i(t+s)$; cf. the remark after (7). To understand the meaning of the second term, we recall that an input spike arriving before an output spike (i.e., $s < 0$) raises the output firing rate by an amount proportional to $\epsilon(-s)$; cf. Fig. 5. The sum in (9) contains the mean contributions of all synapses to an output spike at time $t$. For the proof of (9), we refer to App. A.

![Fig. 4. The postsynaptic potential $\epsilon$ in units of $[e^{-\tau_s}]$ as a function of time $s$ in milliseconds. We have $\epsilon \equiv 0$ for $s < 0$ so that $\epsilon$ is causal. The kernel $\epsilon$ has a single maximum at $s = \tau_0$. For $s \to \infty$ the postsynaptic potential $\epsilon$ decays exponentially with time constant $\tau_s$; cf. also App. B 2.](image-url)
FIG. 5. Spikes–spike correlations. To understand the meaning of Eq. (9) we have sketched $(S_\nu^{in}(t') S_\nu^{out}(t))/\lambda_\nu(t')$ as a function of time $t$ (full line). The dot-dashed line at the bottom of the graph is the contribution $J_j(t')\epsilon(t'-\tau')$ of an input spike occurring at time $\tau'$. Adding this contribution to the mean rate contribution, $\nu_0 + \sum J_j(t)\lambda^{in}_j(t)$ (dashed line), we obtain the rate inside the square brackets of (9) (full line). At time $t'' > \tau'$ the input spike at time $\tau'$ enhances the output firing rate by an amount $J_j(t')\epsilon(t''-\tau')$ (arrows). Note that in the main text we have taken $t'' - \tau' = -s$.

Inserting (9) in (3) we obtain

$$C_i(s; t) = \sum_{j=1}^{N} J_j(t) \lambda^{in}_j(t) + \lambda^{in}_j(t) [v_0 + J_j(t)\epsilon(-s)] ,$$

where we have assumed the weights $J_j$ to be constant in the time interval $[t, t + T]$. Temporal averages are denoted by a bar; cf. Sec. II.C. Note that $\lambda^{in}_j(t) = \nu^{in}_j(t)$.

B. Learning Equation

Before inserting the correlation function (10) into the learning rule (4) we define the covariance matrix

$$q_{ij}(s; t) := [\lambda^{in}_i(t+s) - \nu^{in}_i(t+s)] [\lambda^{in}_j(t) - \nu^{in}_j(t)]$$

and its convolution with the learning window $W$,

$$Q_{ij}(t) := \int_{-\infty}^{\infty} ds W(s) q_{ij}(s; t) .$$

Using (7), (10) and (12) in (4) we obtain

$$J_i = w^{in} \nu^{in} + w^{out} [v_0 + \sum_j J_j \nu_j] + W(0) \nu^{in} v_0 + \sum_j Q_{ij} + W(0) \nu^{in} \nu_j + \delta_{ij} \nu^{in} \int_{-\infty}^{\infty} ds W(s) \epsilon(-s) .$$

For the sake of brevity, we have omitted the dependence upon time.

The assumption of identical and constant mean input rates, $\nu^{in}_i(t) = \nu^{in}$ for all $i$, reduces the number of free parameters in (13) considerably and eliminates all effects coming from rate coding. We define

$$k_1 = [W(0) \nu^{in}] \nu_0 + w^{in} \nu^{in} ,$$

$$k_2 = [W(0) \nu^{in}] \nu^{in} ,$$

$$k_3 = \nu^{in} \int_{-\infty}^{\infty} ds W(s) \epsilon(-s) ,$$

in (13) and arrive at

$$J_i = k_1 + \sum_j (Q_{ij} + k_2 + k_3 \delta_{ij}) J_j .$$

Equation (15) describes the ensemble averaged dynamics of synaptic weights for a spike-based Hebbian learning rule (1) under the assumption of a linear inhomogeneous Poissonian model neuron.

C. Relation to Linsker’s Equation

Linsker [3] has derived a mathematically equivalent equation starting from (5) and a linear graded-response neuron, a rate-based model. The difference between Linsker’s equation and (15) is, apart from a slightly different notation, the term $k_3 \delta_{ij}$.

Equation (15) without the $k_3$ term has been analyzed extensively by MacKay and Miller [5] in terms of eigenvectors and eigenfunctions of the matrix $Q_{ij} + k_2$. In principle, there is no difficulty in incorporating the $k_3$ term in their analysis, because $Q_{ij} + k_2 + \delta_{ij} k_3$ contains $k_3$ times the unit matrix and thus has the same eigenvalues as $Q_{ij} + k_2$. All eigenvalues are simply shifted by $k_3$.

The $k_3$ term can be neglected, if the number $N$ of synapses is large. More specifically, the influence of the $k_3$ term as compared to the $k_2$ and $Q_{ij} \epsilon_j$ term is negligible, if for all $i$

$$\sum_j |Q_{ij} + k_2| J_j \gg |k_3| J_i .$$

This holds, for instance, if (i) we have many synapses, (ii) $|k_3|$ is smaller than or at most of the same order of magnitude as $|k_2 + Q_{ij}|$ for all $i$ and $j$, and (iii) each synapse is weak as compared to the total synaptic weight, $J_i \ll \sum_j J_j$. The assumptions (i)–(iii) are often reasonable neurobiological conditions, in particular, when the pattern of synaptic weights is still unstructured. The analysis of (15) presented in Sec. V and focusing on normalization and structure formation is therefore based on these assumptions. In particular, we neglect $k_3$.

Nevertheless, our approach even without the $k_3$ term is far more comprehensive than Linsker’s rate-based ansatz (5) because we have derived (15) from a spike-based
learning rule (1). Therefore correlations between spikes on time scales down to milliseconds or below can enter the driving term $Q_{ij}$ so as to account for structure formation. Correlations on time scales of milliseconds or below may be essential for information processing in neuronal systems; cf. Sec. III C. In contrast to that, Linsker’s ansatz is based on a firing-rate description where the term $Q_{ij}$ contains correlations between mean firing rates only. If we use a standard interpretation of rate coding, a mean firing rate corresponds to a temporally averaged quantity which varies on a time scale of the order of hundreds of milliseconds. The temporal structure of spike trains is neglected completely.

Finally, our ansatz (1) allows the analysis of the influence of noise on learning. Learning results from stepwise weight changes. Each weight performs a random walk whose expectation value is described by the ensemble averaged equation (15). Analysis of noise as a deviation from the mean is deferred to Sec. VI.

D. Stabilization of Learning

We now discuss the influence of the $k_3$ term in (15). It gives rise to an exponential growth or decay of weights, depending on the sign of $k_3$. Since firing rates $\nu$ are always positive and $k_3 = \nu^m \int ds W(s) \epsilon(-s)$, the sign of the integral $\int ds W(s) \epsilon(-s)$ is crucial. Hebb’s principle suggests that for excitatory synapses, the integral is always positive. To understand why, let us recall that $s$ is defined as the time difference between input and output spikes. The response kernel $\epsilon$ vanishes for negative arguments. Thus the integral effectively runs only over negative $s$. According to our definition, $s < 0$ implies that presynaptic spikes precede postsynaptic firing. These are the spikes that may have participated in firing the postsynaptic neuron. Hebb’s principle [1] suggests that these synapses are strengthened, hence $W(s) > 0$ for $s < 0$; cf. Fig.6. This idea is also in agreement with recent neurobiological results [25,26,33]: Only those synapses are potentiated where presynaptic spikes arrive few milliseconds before a postsynaptic spike occurs so that the former arrive “in time”. We conclude that $\int ds W(s) \epsilon(-s) > 0$ and, hence, the $k_3$ term is positive.

With $k_3 > 0$ every weight and thus every structure in the distribution of weights is enhanced. This may contribute to the stability of structured weight distributions at the end of learning, in particular, when the synapses are few and strong [22,54]. In this case, (16) may be not fulfilled and the $k_3$ term in (15) has an important influence. Thus spike-based learning is different from simple rate-based learning rules. Spike-spike correlations on a millisecond time scale play an important role and tend to stabilize existing strong synapses.

V. LEARNING DYNAMICS

In order to get a better understanding of the principal features of the learning dynamics, we discuss (15) with $k_3 = 0$ for a particularly simple configuration: a model with two groups of synapses. Input rates are homogeneous within each group but different between one group and the other. Our discussion focuses on intrinsic normalization of output rates and structure formation. We take lower and upper bounds for the $J$ values into account explicitly and consider the limiting case of weak correlations in the input. We will see that for a realistic scenario we need to require $w^{in} > 0$ and $w^{out} < 0$ and that we can formulate theoretical predictions of the relative magnitude of the learning parameters $w^{in}, w^{out}$ and the form of the learning window $W$. The theoretical considerations are illustrated by numerical simulations whose parameters are justified in App.B and summarized in Table I.

A. Models of Synaptic Input

We divide the $N$ statistically independent synapses, all converging onto the same neuron, into two groups, $M_1$ and $M_2$. The number of synapses are $M_1$ and $M_2$, respectively, where $M_1 + M_2 = N$ and $M_1, M_2 \gg 1$. Since each group contains many synapses we may assume that $M_1$ and $M_2$ are of the same order of magnitude. The spike input at synapses $i$ in group $M_1$ is generated by a Poisson process with a constant intensity $\lambda_i^{in}(t) \equiv \nu^{in}$, which is independent of $t$. We therefore have $Q_{ij}(t) \equiv 0$ for $i \neq j \in M_1$; cf. Eqs. (11) and (12). The synapses $i$ in group $M_2$ are driven by an arbitrary time-dependent input, $\lambda_i^{out}(t) = \lambda^{out}(t)$, with the same mean input rate.
\( \nu_{in} = \bar{\lambda}^n(t) \) as in group \( M_1 \). Without going into details about the dependence of \( \lambda^m(t) \) upon the time \( t \) we assume \( \lambda^m(t) \) to be such that the covariance \( q_{ij}(s;t) \) in (11) is independent of \( t \). In this case it follows from (12) that \( Q_{ij}(t) \equiv Q \) for \( i, j \in M_2 \), whatever \( t \). For the sake of simplicity we require in addition that \( Q > 0 \). In summary, we suppose in the following

\[
Q_{ij}(t) = \begin{cases} 
Q > 0 & \text{for } i, j \in M_2 \\
0 & \text{otherwise}.
\end{cases}
\]  

(17)

We recall that \( Q_{ij} \) is a measure of the correlations in the input arriving at synapses \( i \) and \( j \); cf. (11) and (12). Equation (17) states that at least some of the synapses receive positively correlated input, a rather natural assumption. Three different realizations of (17) are now discussed in turn.

1. White-Noise Input

For all synapses in group \( M_2 \), let us consider the case of stochastic white noise input with intensity \( \lambda^m(t) \) and mean firing rate \( \bar{\lambda}^m(t) = \bar{\nu}^m(t) \geq 0 \). The fluctuations are

\[
[\bar{\lambda}^m(t + s) - \bar{\nu}^m(t + s)] [\bar{\lambda}^m(t) - \bar{\nu}^m(t)] = c_0 \delta(s).
\]

Due to the convolution (8) with \( \epsilon(s) \), (11) yields \( q_{ij}(s;t) = c_0 \epsilon(-s) \), independently of \( t \), \( i \) and \( j \). We use (12) and find \( Q_{ij}(t) \equiv Q = c_0 \int ds W(s) \epsilon(-s) \). We want \( Q > 0 \) and therefore arrive at \( \int W(s) \epsilon(-s) = k_0 \int \bar{\nu}^m > 0 \). We have seen before in Sec. IVD that \( k_0 \) is a natural assumption and in agreement with experiments.

2. Colored-Noise Input

Let us now consider the case of an instantaneous and memoryless excitation, \( \epsilon(s) = \delta(s) \). We assume that \( \lambda^n - \nu^n \) obeys a stationary Ornstein-Uhlenbeck process [62] with correlation time \( \tau_c \). The fluctuations are therefore

\[
q_{ij}(s;t) \propto \exp\left(-\frac{|s|}{\tau_c}\right), \text{ independently of the synaptic indices } i \text{ and } j.
\]

\( Q > 0 \) implies \( \int ds W(s) \exp\left(-|s|/\tau_c\right) > 0 \).

3. Periodic Input

Motivated by oscillatory neuronal activity in the auditory system and in the cortex (cf. Sec. III C), we now consider the scenario of periodically modulated rates

\[
[\lambda^m(t) - \nu^m] = \delta^m \cos(\omega t), \text{ where } \omega > 2\pi/T.
\]

Let us first study the case \( \epsilon(s) = \delta(s) \). We find

\[
Q = (\delta^m)^2/2 \int ds W(s) \cos(\omega s).
\]

Positive \( Q \) hence requires the real part of the Fourier transform \( \tilde{W}(\omega) := \int ds W(s) \exp(i\omega s) \) to be positive, i.e., \( \Re[\tilde{W}(\omega)] > 0 \). For a general interaction kernel \( \epsilon(s) \), we find

\[
q_{ij}(s;t) = (\delta^m)^2/2 \int ds \epsilon(s') \cos[\omega (s + s')]
\]

and hence

\[
Q = (\delta^m)^2/2 \Re[\tilde{W}(\omega) \tilde{\epsilon}(\omega)],
\]  

(18)

whatever of \( t \). Then \( Q > 0 \) requires \( \Re[\tilde{W}(\omega) \tilde{\epsilon}(\omega)] > 0 \).

B. Normalization

Normalization is a very desirable property for any learning rule. It is a natural requirement that the average weight and the mean output rate do not blow up during learning but are stabilized at a reasonable value in an acceptable amount of time. Standard rate-based Hebbian learning can lead to unlimited growth of the average weight. Several methods have been designed to control this unlimited growth; for instance, subtractive or multiplicative rescaling of the weights after each learning step so as to impose either \( \sum_j J_j = \text{const.} \) or else \( \sum_j J_j^2 = \text{const.} \), cf., e.g., [2, 7, 55]. It is hard to see, however, where this should come from. Furthermore, a \( J \) dependence of the parameters \( a_1, \ldots, a_5 \) in the learning equation (5) is often assumed. Higher-order terms in the expansion (5) may also be used to control unlimited growth.

In this subsection we show that under some mild conditions there is no need whatsoever to invoke the \( J \) dependence of the learning parameters, rescaling of weights, or higher-order correlations to get normalization, which means here that the average weight

\[
f^\text{av} = \frac{1}{N} \sum_{i=1}^{N} J_i
\]  

(19)

approaches a stable fixed point during learning. Moreover, in this case the mean output rate \( \nu^\text{out} \) is also stabilized since \( \nu^\text{out} = \nu_0 + N J^\text{av} \nu^m \), cf. (7).

As long as the learning parameters do not depend on the \( J \) values, the rate of change of the average weight is obtained from (15), (19), and \( k_0 = 0 \) (Sec. IV C),

\[
f^\text{av} = \frac{1}{N} \sum_{i,j} Q_{ij} J_j.
\]  

(20)

In the following we consider the situation at the beginning of the learning procedure where the set of weights \{\( J \)\} have not picked up any correlations with the set of Poisson intensities \{\( \lambda^m \)\} yet and therefore are independent. We may then replace \( J_i \) and \( Q_{ij} \) on the right-hand side of (20) by their average values \( J^\text{av} \) and \( Q^\text{av} = N^{-2} \sum_{i,j} Q_{ij} \), respectively. The specific input (17) described in the previous section yields

\[
Q^\text{av} = (M_2/N)^2 Q > 0.
\]

We rewrite (20) in the standard form

\[
f^\text{av} = [J^\text{av} - J^\text{mv}] / \tau^\text{av},
\]

where

\[
j^\text{av} = -k_1 / [N (k_2 + Q^\text{av})]
\]  

(21)

is the fixed point for the average weight and

\[
\tau^\text{av} = j^\text{av} / k_1 = -1 / [N (k_2 + Q^\text{av})]
\]  

(22)

is the time constant of normalization. The fixed point in (21) is stable, if and only if \( \tau^\text{av} > 0 \).

During learning, weights \{\( J \)\} and rates \{\( \lambda^m \)\} may become correlated. In App. C we demonstrate that the influence of any interdependence between weights and rates

8
on normalization can be neglected in the case of weak correlations in the input,

$$0 < Q \ll -k_2.$$  \hspace{1cm} (23)

The fixed point \( J^\infty \) in (21) and the time constant \( \tau^\infty \) in (22) are, then, almost independent of the average correlation \( Q^\infty \), which is always of the same order as \( Q \).

In Figs. 7 and 8 we show numerical simulations with parameters as given in App. B. The average weight \( J^\infty \) always approaches \( J^\infty \), independently of any initial conditions in the distribution of weights.

![Numerical simulation of weight normalization](image)

**FIG. 7.** Numerical simulation of weight normalization with parameters as given in App. B. The four graphs show the temporal evolution of synaptic weights \( J_i \), \( 1 \leq i \leq 50 \), before \( (t = 0) \) and during learning \( (t = 200, 500, \) and 1000 seconds). Before learning, all weights are initialized at the upper bound \( \vartheta = 0.1 \). During learning, weights decrease towards the fixed point of the average weight, \( J^\infty = 2.0 \cdot 10^{-3} \), cf. also Fig. 8, topmost full line. The time constant of normalization is \( \tau^\infty = 2.0 \cdot 10^{-3} \) s, which is much smaller than the time constant of structure formation; cf. Sec. V C and Fig. 9. For times \( t \leq 1000 \) s we therefore can neglect effects coming from structure formation.

![Development of the average weight](image)

**FIG. 8.** Development of the average weight \( J^\infty \) as a function of time \( t \) in units of \( 10^3 \) seconds. The simulations we started at \( t = 0 \) with five different average weights, \( J^\infty = (0.01, 0.02 = J^\infty, 0.05, 0.1 = \vartheta) \). Full lines indicate homogeneous initial weight distributions, where \( J_i = J^\infty \) at \( t = 0 \) for all \( i \); cf. also Fig. 7, upper left panel. In all five cases, \( J^\infty \) decays with the time constant \( \tau^\infty = 2.0 \cdot 10^{-3} \) s describing the rate of normalization to the fixed point \( J^\infty = 2.0 \cdot 10^{-2} \).

Our theoretical prediction according to Sec. V B (crosses on the uppermost full line) is in good agreement with the numerical results. The dashed line indicates the development of \( J^\infty \) starting from an inhomogeneous initial weight distribution \( J_i = 0 \) for \( 1 \leq i \leq 25 \) and \( J_i = \vartheta \) for \( 25 < i \leq 50 = N \). In the inhomogeneous case, \( \tau^\infty \) is enlarged as compared to the homogeneous case by a factor of 2 because only half of the synapses are able to contribute to normalization; cf. App. D.

The insets (signatures as in Fig. 7) show the inhomogeneous weight distributions (arrows) at times \( t = 200, 500, \) and 1000s; the dotted line indicates the fixed point \( J^\infty = 0.2 \vartheta \). We note that here the distribution remains inhomogeneous.

**Weight Constraints Lead to Further Conditions on Learning Parameters**

We have seen that normalization is possible without a \( J \) dependence of the learning parameters. Even if the average weight \( J^\infty \) approaches a fixed point \( J^\infty \), there is no restriction on the size of individual weights, apart from \( J_i \geq 0 \) for excitatory synapses and \( J_i \leq N J^\infty \). This means that a single weight at most comprises the total (normalized) weight of all \( N \) synapses. The latter case is, however, unphysiological, since almost every neuron holds many synapses with nonvanishing efficacies (weights) and efficacies of biological synapses seem to be limited. We take this into account in our learning rule by introducing a hard upper bound \( \vartheta \) for each individual weight. As we will demonstrate, a reasonable value of \( \vartheta \) does not influence normalization in that \( J^\infty \) remains unchanged. However, an upper bound \( \vartheta > 0 \), whatever its value, leads to further constraints on the learning parameters.

To incorporate the restricted range of individual weights into our learning rule (1), we assume that we can treat the learning parameters \( w^{in}, w^{out} \), and the amplitude of \( W \) to be constant in the range \( 0 \leq J_i \leq \vartheta \). For \( J_i < 0 \) or \( J_i > \vartheta \), we take \( w^{in} = w^{out} = W = 0 \). In other words, we use (15) only between the lower bound 0 and the upper bound \( \vartheta \) and set \( dJ_i/dt = 0 \), if \( J_i < 0 \) or \( J_i > \vartheta \).

Because of lower and upper bounds for each synaptic weight, \( 0 \leq J_i \leq \vartheta \) for all \( i \), a realizable fixed point \( J^\infty \) has to be within these limits. Otherwise all weights saturate either at the lower or at the upper bound. To avoid this, we first of all need \( J^\infty > 0 \). Since \( \tau^\infty = J^\infty/k_1 \) in (22) must be positive for stable fixed points, we also need \( k_1 > 0 \). The meaning becomes transparent from (14) in the case of vanishing spontaneous activity...
in the output, \( v_0 = 0 \). Then \( k_1 > 0 \) reduces to
\[ w_{\text{in}} > 0, \]
which corresponds to neurobiological reality [28,56,31].

A second condition for a realizable fixed point arises from the upper bound \( \vartheta > J_{\text{av}}^w \). This requirement leads to \( k_2 < -k_1/(N\vartheta) - Q_{\text{av}} \). Exploiting only \( k_2 < 0 \), we find from (14) that \( w_{\text{out}} + \hat{W}(0) w_{\text{in}} < 0 \), which means that postsynaptic spikes on average reduce the total weight of synapses. This is one of our predictions that can be tested experimentally. Assuming \( \hat{W}(0) > 0 \), which seems reasonable — with the benefit of hindsight — in terms of rate-coded learning à la Hebb (Sec. III), we predict
\[ \frac{w_{\text{out}}}{< 0}, \]
which has not been verified by experiments yet.

Weight constraints do not influence the position of the fixed point \( J_{\text{av}}^w \) (as long as it remains realizable) but may enlarge the value of the time constant \( \tau_{\text{av}} \) of normalization (see details in App. D). The time constant \( \tau_{\text{av}} \) changes because weights saturated at the lower (upper) bound cannot contribute to a decrease (increase) of \( J_{\text{av}}^w \). If fewer than the total number of weights add to our (subtractive) normalization, then the fixed point is approached more slowly; cf. Fig. 8, dashed line and insets. The factor, however, by which \( \tau_{\text{av}} \) may be enlarged is of order 1, if we take the upper bound to be \( \vartheta = (1 + d) J_{\text{av}}^w \), where \( d > 0 \) is of order 1, which will be assumed throughout what follows; cf. App. D.

C. Structure Formation

In our simple model with two groups of input, structure formation can be measured by the difference \( J_{\text{str}}^w \) between the average synaptic strength in groups \( \mathcal{M}_1 \) and \( \mathcal{M}_2 \); cf. Sec. VA. We derive conditions under which this difference increases during learning. In the course of the argument we also show that structure formation takes place on a time scale \( \tau_{\text{str}} \) considerably slower than the time scale \( \tau_{\text{av}} \) of normalization.

We start from (15) with \( k_3 = 0 \) and randomly distributed weights. For the moment we assume that normalization has already taken place. Furthermore, we assume small correlations as in (23), which assures that the fixed point \( J_{\text{av}}^w \approx -k_1/(Nk_2) \) is almost constant during learning; cf. (21) and (C1). If the formation of any structure in \( \{ k_i \} \) is slow as compared to normalization, we are allowed to use \( J_{\text{av}} = J_{\text{str}}^w \) during learning. The consistency of this ansatz is checked at the end of this section.

The average weight in each of the two groups \( \mathcal{M}_1 \) and \( \mathcal{M}_2 \) is
\[ J^{(1)} = \frac{1}{M_1} \sum_{i \in \mathcal{M}_1} J_i \quad \text{and} \quad J^{(2)} = \frac{1}{M_2} \sum_{i \in \mathcal{M}_2} J_i. \]

If lower and upper bounds do not influence the dynamics of each weight, the corresponding rates of change are
\[ J^{(1)} = k_1 + M_1 J^{(1)} - k_2 + M_2 J^{(2)}, \]
\[ J^{(2)} = k_1 + M_2 J^{(2)} - k_2 + M_1 J^{(1)}. \]

One expects the difference \( J_{\text{str}} = J^{(2)} - J^{(1)} \) between those average weights to grow during learning because group \( \mathcal{M}_2 \) receives a stronger reinforcement than \( \mathcal{M}_1 \). Differentiating \( J_{\text{str}} \) with respect to time, using (27) and the constraint \( J_{\text{av}} = N^{-1} (M_1 J^{(1)} + M_2 J^{(2)}) \), we find the rate of growth
\[ J_{\text{str}} = \frac{M_1 M_2}{N} Q J_{\text{str}} + M_2 Q J_{\text{av}}. \]

The first term on the right-hand side gives rise to an exponential increase \( (Q > 0) \) while the second term gives rise to a linear growth of \( J_{\text{str}} \). Equation (28) has an unstable fixed point at \( J_{\text{str}}^* = -N/M_1 J_{\text{av}} \). Note that \( J_{\text{str}}^* \) is always negative and independent of \( Q \).

We associate the time constant \( \tau_{\text{str}} \) of structure formation with the time that is necessary for an increase of \( J_{\text{str}} \) from a typical initial value to its maximum. The maximum of \( J_{\text{str}} \) is of order \( J_{\text{str}}^* \), if \( M_1/M_2 \) is of order 1 (Sec. VA) and if \( \vartheta = (1 + d) J_{\text{av}} \), where \( d > 0 \) is of order 1 (Sec. VB). At the beginning of learning \((t = 0)\), we may take \( J_{\text{str}}(0) = 0 \). Using this initial condition, an integration of (28) leads to \( J_{\text{str}}(t) = (N/M_1) J_{\text{str}}^*[\exp(tM_1M_2Q/N) - 1] \). With \( t = \tau_{\text{str}} \) and \( J_{\text{str}}(\tau_{\text{str}}) = J_{\text{str}}^* \) we obtain \( \tau_{\text{str}} = N/(M_1M_2Q) \log(M_1/N + 1) \). Since we only need an estimate of \( \tau_{\text{str}} \) we drop the logarithm, which is of order 1. Finally, approximating \( N/(M_1M_2) \) by \( 1/N \) we arrive at the estimate
\[ \tau_{\text{str}} = (NQ)^{-1}. \]

We could adopt a refined analysis similar to the one we have used for \( J_{\text{av}} \) to discuss the effects of the upper and lower bounds for individual weights. We will not do so, however, since the result (29) suffices for our purpose: the comparison of time constants.

A comparison of \( \tau_{\text{av}} \) in (22) with \( \tau_{\text{str}} \) in (29) shows that we have a separation of the fast time scale of normalization from the slow time scale of structure formation, if (23) holds. A numerical example confirming the above theoretical considerations is presented in Fig. 9. Simulation parameters are as given in App. B.
D. Stabilization of Learning

Up to this point we have neglected the influence of the $k_3$ term in (15), which may lead to a stabilization of weight distributions, in particular, when synapses are few and strong [22, 54]; cf. Sec. IV D. This is the case, for example, in the scenario of Fig. 10, which is the final result of the simulations described in Fig. 9. The shown weight distribution is stable so that learning has terminated apart from minor rapid fluctuations due to noise.

FIG. 9. Temporal evolution of average weights $J^{(w)}$, $J^{(1)}$, and $J^{(2)}$ as a function of the learning time $t$ in units of $10^3$ seconds. The quantity $J^{(w)}$ is the average weight of all synapses, $J^{(1)}$ and $J^{(2)}$ are average weights in groups $M_1$ and $M_2$, respectively. Synapses $i$ in group $M_1$, where $1 \leq i \leq 25$, receive incoherent input whereas synapses $i$ in group $M_2$, where $26 \leq i \leq 50$, are driven by a coherently modulated input intensity. Parameters are as given in App. B. Simulations started at time $t = 0$ with a homogeneous weight distribution $J_t = \bar{\theta} = 0.1$ for all $i$. The normalization of the average weights takes place within a time of order $O(100 \text{s})$; see also the uppermost full line in Fig. 8. On the time scale of $\tau^{\text{st}} = 2.93 \cdot 10^4 \text{s}$ a structure in the distribution of weights emerges in that $J^{(2)}$ grows at the expense of $J^{(1)}$. The average weight $J^{(w)}$ remains almost unaffected near $J^{(w)} = 2 \cdot 10^{-2}$ (dashed line). The slight enlargement of $J^{(w)}$ between $t = 10^3 \text{s}$ and $t = 7 \cdot 10^3 \text{s}$ can be explained by using (11) and taking also the $k_3$ term into account. The insets (signatures as in Figs. 7 and 8) show the weight distributions at times $t = 10^3$, $10^4$, $2.93 \cdot 10^4$, and $7 \cdot 10^4 \text{s}$ (arrows).

VI. NOISE

In this section we discuss the influence of noise on the evolution of each weight. Noise may be due to jitter of input and output spikes and the fact that we deal with spikes per second (Sec. III B). This gives rise to a random walk of each weight around the mean trajectory described by (15). The variance $\text{Var} J_i(t)$ of this random walk increases linearly with time as it does in free diffusion. From the speed of the variance increase we derive a time scale $\tau^{\text{noise}}$. A comparison with the time constant $\tau^{\text{st}}$ of structure formation leads to further constraints on our learning parameters and shows that, in principle, any correlation in the input, however weak, can be learnt, if there is enough time available for learning.

The calculation of $\text{Var} J_i$ is based on four approximations. First, we neglect upper and lower bounds of the learning dynamics as we have done for the calculation of the time constants of normalization (Sec. V B) and structure formation (Sec. V C). Second, we neglect spike-spike correlations between input and output and work directly with ensemble-averaged rates. As we have seen, spike-spike correlations show up in the term $k_3$ in (15) and have little influence on learning, given many, weak synapses and an appropriate scenario for our learning parameters; cf. Sec. IV C. Third, we assume constant input rates $\lambda_i^{J}(t) = \bar{\nu}_i^{\text{in}}$ for all $i$. A temporal structure in the input rates is expected to play a minor role here. Fourth, as a consequence of constant input rates we assume a constant output rate $\lambda_i^{\text{out}}(t) = \bar{\nu}_i^{\text{out}}$.

Despite such a simplified approach we can study some interesting effects caused by neuronal spiking. Within the limits of our approximations, input and output spikes...
are generated by independent Poisson processes with constant intensities. The variance \( \text{Var} J_i(t) \) increases basically because of shot noise at the synapses. We now turn to the details.

A. Calculation of the Variance

We start with some weight \( J_i(t_0) \) at time \( t_0 \) and calculate the variance \( \text{Var} J_i(t) := \langle J_i^2(t) \rangle - \langle J_i(t) \rangle^2 \) as a function of \( t \) for \( t > t_0 \). Angular brackets \( \langle \ldots \rangle \) again denote an ensemble average; cf. Sec. II B. A detailed analysis is outlined in App. E. The result is

\[
\text{Var} J_i(t) = (t - t_0) D \quad \text{for} \quad t - t_0 \gg W ,
\]

where \( W \) is the width of the learning window (cf. Sec. II C) and

\[
D = \nu_w \langle W \rangle^2 + \nu_o \langle W \rangle^2 + \nu_{w, o} \int ds W(s)^2 \quad (31)
\]

\[+ \nu_{w, o} \langle W \rangle \left[ (\langle W \rangle^2 + \langle W \rangle^2) + \int ds W(s)^2 \right] ,
\]

Thus because of Poisson spike arrival and stochastic output firing with disjoint intervals being independent, each weight \( J_i \) undergoes a diffusion process with diffusion constant \( D \).

To discuss the dependence of \( D \) upon the learning parameters, we restrict our attention to the case \( \nu_w = \nu_o \) in (31). Since mean input and output rates in biological neurons typically are not too different, this makes sense. Moreover, we do not expect that the ratio \( \nu_w / \nu_o \) is a critical parameter. We recall from Sec. VB that \( \nu_w = -k_1 / k_2 \nu_w \) once the weights are already normalized and if \( v_0 = Q_{\nu w} = 0 \). With \( \nu_w = \nu_o \) this is equivalent to \( k_1 = -k_2 \). Using the definition of \( k_1 \) and \( k_2 \) in (14) we find \( \nu_w = \nu_o = -W(0) \nu_w \). If we insert this into (31), the final term vanishes. In what remains of (31) we identify the contributions due to input spikes, \( \nu_{w} \langle W \rangle \), and output spikes, \( \nu_{o} \langle W \rangle \). Weight changes because of correlations between input and output spikes enter (31) via \( \nu_{w, o} \int ds W(s)^2 \).

Equation (30) describes the time course of the variance of a single weight. Estimating \( \text{Var} J_i \) is numerically expensive because we have to simulate many independent learning trials. It is much cheaper to compute the variance of the distribution \( \{J_i\} \) of weights in a single learning trial. For the sake of a comparison of theory and numerics in Fig. 11, we plot

\[
\text{Var} \{J_i\}(t) := \frac{1}{N - 1} \sum_{i=1}^{N} [J_i(t) - \langle J_i(t) \rangle]^2,
\]

which obeys a diffusion process with

\[
\text{Var} \{J_i\}(t) = (t - t_0) D',
\]

in a way similar to (30). The diffusion constant \( D' \) is, however, different from \( D \) because weights of single neurons do not develop independently of each other. Each output spike triggers the change of all \( N \) weights by an amount \( w_{o, i} \). Therefore, output spikes do not contribute to a change of \( \text{Var} \{J_i\}(t) \) as long as upper and lower bounds have not been reached. Furthermore, all synapses 'see' the same spike train of the postsynaptic neuron they belong to. In contrast to that, input spikes at different synapses are independent. Again we assume that input and output spikes are independent; cf. the second paragraph at the beginning of Sec. VI. Combining the above arguments we obtain the diffusion constant \( D' \) by simply setting \( w_{o, i} = 0 \) and disregarding the term \( \nu_{w, o} \langle W \rangle^2 \) in (31), which leads to

\[
D' = \nu_{w} (\langle W \rangle^2 + \nu_{o} \langle W \rangle \int ds W(s)^2 + 2 \nu_{w, o} \langle W \rangle^2).
\]

The boundaries of validity of (33) are illustrated in Fig. 12.

FIG. 11. Influence of noise. We compare numerical results for the evolution of the variance \( \text{Var} \{J_i\}(t) \) defined in Eq. (32) (full lines) with our theoretical prediction (dashed line) based on (33) with \( D' = 1.47 \times 10^{-5} \text{s}^{-1} \). Learning starts at time \( t = 0 \) with a homogeneous distribution, \( J_i = J_{\mu 0} = 0.02 \) for all \( i \). The thin line corresponds to the simulation of Fig. 8 with initial condition \( J_{\mu 0} = 0.02 \), viz., two groups of 25 synapses each. The thick line has been obtained with incoherent input for all 50 synapses, \( J_{\mu i}(t) = \nu_w \) for all \( i \) (all other parameters in App. B being equal). Because the number of synapses is finite (\( N = 50 \)) deviations from the dashed straight line are due to fluctuations. The overall agreement between theory and simulation is good.
B. Time Scale of Diffusion

The effects of shot noise in input and output show up on a time scale $\tau^{\text{noise}}$ which may be defined as the time interval necessary for an increase of the variance (30) from $\text{Var} \{J_i\}(t_0) = 0$ to $\text{Var} \{J_i\}(t_0 + \tau^{\text{noise}}) = (J^{\text{av}})^2$. We chose $J^{\text{av}}$ as a reference value because it represents the available range for each weight. From (30) we obtain $\tau^{\text{noise}} = (J^{\text{av}})^2 / D$. We use $J^{\text{av}} = -k_1/(Nk_2)$ from (21) and $Q^{\text{av}} = 0$. This yields

$$\tau^{\text{noise}} = \frac{1}{N^2 D} \left( \frac{k_1}{k_2} \right)^2. \quad (34)$$

C. Comparison of Time Scales

We now compare $\tau^{\text{noise}}$ in (34) with the time constant $\tau^{\text{str}} = 1/(NQ)$ of structure formation as it appears in (29). The ratio

$$\frac{\tau^{\text{noise}}}{\tau^{\text{str}}} = \frac{Q}{ND} \left( \frac{k_1}{k_2} \right)^2. \quad (35)$$

should exceed 1 so as to enable structure formation (in the sense of Sec. V C). Otherwise weight diffusion due to noise spreads the weights between the lower bound 0 and the upper bound $\vartheta$ and, consequently, destroys any structure.

We note that $D$ in (35) is quadratic in $w^{\text{in}}, w^{\text{out}}$, and $W$, whereas $k_1, k_2,$ and $Q$ are linear; cf. (12), (14), (17), and (31). As a consequence, scaling $w^{\text{in}}, w^{\text{out}}$, and $W[s]$ for the learning parameter $\eta$ in (1) by a common factor $\gamma$ changes the ratio of time constants in (35) by $\gamma^{-1}/\gamma$ without affecting the (normalized) mean output rate $E_{\text{out}}$ and the fixed points $J^{\text{av}}$ and $J^{\text{av}} = -J^{\text{av}} N/M$; cf. (21). Hence it is always possible to achieve $\tau^{\text{noise}}/\tau^{\text{str}} > 1$ by tuning $\gamma$. This means that any covariance matrix (11) that gives rise to $Q > 0$, however small, can be learnt. More precisely, it can be learnt, if there is enough time for learning.

A reduction of $\gamma$ also increases the time constant $\tau^{\text{str}} = 1/(NQ)$ of structure formation; cf. (29). If the learning time is limited, which may be the case in biological systems, only input with $Q$ larger than some minimal value can be learnt. Considering the learning parameters as fixed, we see that increasing the number of synapses, on the one hand, helps reducing the time $\tau^{\text{str}}$ necessary for learning but, on the other hand, decreases the ratio $\tau^{\text{noise}}/\tau^{\text{str}}$ in (35), possibly below 1.

With parameters as given in App. B the ratio (35) is 5.5. Therefore the desired structure in Fig. 9 can emerge before noise spreads the weights at random.

VII. DISCUSSION

Changes of synaptic efficacies are triggered by the relative timing of presynaptic and postsynaptic spikes [25,26]. The learning rule (1) discussed in this paper is a first step towards a description and analysis of the effects of synaptic changes with single-spike resolution. Our learning rule can be motivated by elementary dynamic processes at the level of the synapse [54,57] and can also be implemented in hardware; cf. [40]. A phenomenological model of the experimental effects which is close to the model studied in the present paper has been introduced [42]. A compartmental model of the biophysics and ion dynamics underlying spike-based learning along the lines of [58] has not been attempted yet. As an alternative to changing synaptic weights, spike-based learning rules which act directly on the delays may also be considered [59-61].

The learning rule (1) discussed in the present paper is rather simple and contains only terms that are linear and quadratic in the pre- and postsynaptic spikes ('Hebbian' learning). This simple mathematical structure, which is based on experiment [25,26,30], has allowed us to derive analytical results and identify some key quantities.

First of all, if the input signal contains no correlations with the output at the spike level, and if we use a linear...
Poissonian neuron model, the spike-based learning rule reduces to (15), which is closely reminiscent of Linsker’s linear learning equation for rate coding [3]. The only difference is an additional term $s_k$, which is not accounted for by pure rate models. It is caused by precise temporal correlations between an output spike and an input spike that has triggered the pulse. This additional term reinforces synapses that are already strong and hence helps to stabilize existing synapse configurations.

In the limit of rate coding, the form of the learning window $W$ is not important because only the integral $\int ds W(s)$ counts: $\int ds W(s) > 0$ would be called “Hebbian”, $\int ds W(s) < 0$ is sometimes called “anti-Hebbian” learning. In general, however, input rates may be modulated on a fast time scale or contain correlations at the spike level. In this case, the shape of the learning window does matter. A learning window with a maximum at $s^* < 0$ (thus maximal increase of the synaptic strength for a presynaptic spike preceding a postsynaptic spike; cf. Fig. 6) picks up the correlations in the input. In this case a structured distribution of synaptic weights may evolve [22].

The mathematical approach developed in this paper leads to a clear distinction between different time scales. First, the fastest time scale is set by the time course of the postsynaptic potential $e$ and the learning window $W$. Correlations in the input may occur on the same fast time scale, but can also be slower or faster, there is no restriction. Second, learning occurs on a much slower time scale and in two phases: (i) an intrinsic normalization of total synaptic weight and the output firing rate followed by (ii) structure formation. Third, if the learning rate is small enough, then diffusion of the weights due to noise is slow as compared to structure formation. In this limit, the learning process is described by the differential equation (4) for the expected weights.

Normalization is possible, if at least $w^{in} > 0$ and $w^{out} < 0$ for $\int ds W(s) > 0$ in (1) (“Hebbian” learning). In this case, the average weight may decay exponentially to a fixed point, though there is no decay term for individual weights. In other words, normalization is an intrinsic property since we do not invoke multiplicative or subtractive rescaling of weights after each learning step [2,7,55].

The fluctuations due to noise have been treated rather crudely in the present paper. In principle, it should be possible to include the effects of noise directly at the level of the differential equation, as is standard in statistics [62]. Such an approach would then lead to a Fokker-Planck equation for the evolution of weights as discussed in [63]. All this is in principle straightforward but in practice very cumbersome.

Finally, we emphasize that we have used a crudely oversimplified neuron model, viz., a linear stochastic unit. In particular, there is no spike emission threshold nor reset or spike afterpotential. Poisson firing is not as realistic as it may at first seem, though. Large networks of integrate-and-fire neurons with stochastic connectivity exhibit Poisson-like firing [64]. Experimental spike interval distributions are also consistent with Poisson firing [65]. In the present paper, the simple Poisson model has been chosen so as to grasp the mathematics and get an explicit expression for the correlation between input and output spikes. The formulation of the learning rule and the derivation of the learning equation (4) is general and holds for any neuron model. The calculation of the correlations which enter in the definition of the parameter $Q_{ij}$ in (15) are, however, much more difficult, if a nonlinear neuron model is used.

Spike-based Hebbian learning has important implications for the question of neural coding since it allows to pick up and stabilize fast temporal correlations [38,22,41]. A better understanding of spike-triggered learning may thus also contribute to a resolution of the problem of neural coding [17,19,65-67].

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APPENDIX A: PROOF OF EQUATION (9)

In proving Eq. (9) there is no harm in putting $v_0 = 0$. We then have to compute the average

$$\langle S_i^{in}(t+s) S^{out}_{j}(t) \rangle$$

(A1)

where $f_{j}(t) = J_{i}(t) \sum_{f} \epsilon(t - t_{f}^{j})$ with the upper index $f$ ranging over the firing times $t_{f}^{j} < t$ of neuron $i$, that has an axonal connection to synapse $j$; here $1 \leq i \leq N$. Since $\epsilon$ is causal, i.e., $\epsilon(s) \equiv 0$ for $s < 0$, we can drop the restriction $t_{f}^{j} < t$. The synapses being independent of each other, the sum over $j(\neq i)$ is independent of $S_i^{in}$ and thus we obtain

$$\langle S_i^{in}(t+s) \rangle$$

(A2)

$$= \langle S_i^{in}(t+s) \langle \sum_{j(\neq i)} f_{j}(t) \rangle \rangle$$

$$= \lambda^{in}_{i}(t+s) \sum_{j(\neq i)} J_{j}(t) \int_{0}^{\infty} dt' e(t') \lambda^{out}_{j}(t-t')$$.
The term $\langle S^i_{\text{in}}(t+s) f_i(t) \rangle$ in (A1) has to be handled with more care as it describes the influence of synapse $i$ on the firing behavior of the postsynaptic neuron.

$$\langle S^i_{\text{in}}(t+s) f_i(t) \rangle = \left\langle \sum_j \delta(t+s-t'_j) \left[ J_i(t) \sum_j \epsilon(t-t'_j) \right] \right\rangle,$$

(A3)

The first term on the right in (A3) samples spike events at time $t+s$. To be mathematically precise, we sample all spikes in a small interval of size $\Delta t$ around $t+s$, average, and divide by $\Delta t$. We replace the first sum in (A3) by the (approximate) identity $(\Delta t)^{-1} \sum \delta(t+s-t'_j)$, where $1_{\{\ldots\}}$ is the indicator function of the set $\{\ldots\}$; i.e., it equals 1 when its argument is in the set $\{\ldots\}$ and 0 elsewhere. Because the postsynaptic potential $\epsilon$ is a continuous function we approximate the second sum by $\sum_k 1_{\{\text{spike in } [t_k, t_k + \Delta t)\}} \epsilon(t-t_k)$, where $\{t_k, t_k + \Delta t, k \in \mathbb{Z}\}$ is a decomposition of the real axis. Since it is understood that $\Delta t \to 0$, all events with two or more spikes in an interval $[t_k, t_k + \Delta t]$ have a probability of $O(\Delta t)$ and, hence, can be neglected. It is exactly this property that is typical to a Poisson process and to any biological neuron.

What we are going to compute is the correlation between $S^i_{\text{in}}$, the input at synapse $i$, and the output $S^\text{out}$, that is governed by all synapses, including synapse $i$. Here the simplicity of the linear Poissonian neuron model pays off as $S^\text{out}$ is linear in the sum of the synaptic inputs and, hence, in each of them. Furthermore, whatever the model, the synaptic efficacies $J_i(t)$ are changing adiabatically with respect to the neuronal dynamics so that they can be taken to be constant and, thus, out of the average. In the limit $\Delta t \to 0$ we can therefore rewrite the right-hand side of (A3) so as to find

$$J_i(t) (\Delta t)^{-1} \sum_k \epsilon(t-t_k)$$

(A4)

$$\times \left\langle 1_{\{\text{spike in } [t_k, t_k + \Delta t)\}} \right\rangle \left\langle 1_{\{\text{spike in } [t_k, t_k + \Delta t)\}} \right\rangle.$$

Without restriction of generality we can choose our partition so that $t_k = s + t$ for some $k$, say $k = l$. Singling out $k = l$, the rest ($k \neq l$) can be averaged directly, since events in disjoint intervals are independent. Because $1_{\{\ldots\}} = \sum \delta(t+s-t'_j)$, the result is $J_i(t) \sum \epsilon(t-t'_j)$, where we have used $\langle \delta \rangle$.

As for the term $k = l$, we plainly have $1_{\{\ldots\}} = 1_{\{\ldots\}}$, as an indicator function assumes only two distinct values, 0 and 1. We obtain $J_i(t) \sum \epsilon(t-t'_j)$.

Collecting terms and incorporating $\nu_0 \neq 0$ we find (9).

**APPENDIX B: PARAMETERS FOR NUMERICAL SIMULATIONS**

We discuss the parameter regime of the simulations as shown in Secs. V and VI. Numerical values and important derived quantities are summarized in Table I.

1. **Learning Window**

We use the learning window

$$W(s) = \eta \left\{ \exp \left( -\frac{s}{\tau_+} \right) + A_+ \left( 1 - \frac{s}{\tau_+} \right) \right\} \text{ for } s \leq 0$$

$$\left. \quad + A_+ \exp \left( -\frac{s}{\tau_-} \right) + A_- \exp \left( -\frac{s}{\tau_-} \right) \right\} \text{ for } s > 0.$$

(B1)

Here $s$ is the delay between presynaptic spike arrival and postsynaptic firing, $\eta$ is a "small" learning parameter, $\tau^{\text{syn}}$, $\tau_+$, $\tau_-$, $\tau_+: = \tau^{\text{syn}}/\tau_+ + \tau_-$, and $\tau_-: = \tau^{\text{syn}}/\tau_- + \tau_-$ are time constants. The dimensionless constants $A_+$ and $A_-$ determine the strength of synaptic potentiation and depression, respectively. Numerical values are $\eta = 10^{-5}$, $\tau^{\text{syn}} = 5 \text{ ms}$, $\tau_+ = 1 \text{ ms}$, $\tau_- = 20 \text{ ms}$, and $A_+ = 1$, $A_- = -1$; cf. Table I. The learning window (cf. Fig. 6) is in accordance with experimental results [25, 26, 28, 29, 33]. A detailed explanation of our choice of the learning window on a microscopical basis of Hebbian learning can be found elsewhere [54, 57].

For the analysis of the learning process we need the integrals $\int ds W(s) = \int ds W(s)^2$. The numerical result is listed in Table I. Using $c_+: = \tau^{\text{syn}}/\tau_+$ and $c_-: = \tau^{\text{syn}}/\tau_- \Rightarrow$ we obtain

$$\int ds W(s) = \eta \tau^{\text{syn}} \left[ A_+ (2 + c_- + c_-^{-1}) \right]$$

$$+ A_+ (2 + c_+ + c_+^{-1})$$

(B2)

and

$$\int ds W(s)^2 = \frac{\eta^2}{4} \left[ A_+^2 \tau_+ \left[ c_+^2 + 4c_+^2 + 5c_+ + 2 \right] \right]$$

$$+ A_+ \tau_+ \left[ c_+^2 + 4c_+^2 + 5c_+ + 2 \right]$$

$$+ 2 A_+ A_- \tau^{\text{syn}} \left[ c_+ c_- + 2 (c_+ + c_-) \right]$$

$$+ 5 + 4/(c_+ + c_-) \right\}.$$

(B3)

2. **Postsynaptic Potential**

We use the excitatory postsynaptic potential (EPSP)

$$\epsilon(s) = s/\tau_0^2 \exp(\epsilon \tau_0) \text{ } H(s),$$

(B4)

where $H(.)$ denotes the Heaviside step function, and $\int ds \epsilon(s) = 1$. For the membrane time constant we use $\tau_0 = 10 \text{ ms}$, which is reasonable for cortical neurons [68, 69]. The EPSP has been plotted in Fig. 4. Using (B1) and (B4) we obtain

$$\int ds W(s) \epsilon(s) \left[ \epsilon(\tau^{\text{syn}})^2 / (\tau^{\text{syn}} + \tau_0)^3 \right]$$

$$\times \left[ A_+ (2 \tau^{\text{syn}} \tau_+ / \tau_+ + \tau^{\text{syn}} + 3 \tau_0) \right.$$

$$+ A_+ (2 \tau^{\text{syn}} \tau_0 / \tau_+ + \tau^{\text{syn}} + 3 \tau_0) \right].$$

(B5)
3. Synaptic Input

The total number of synapses is \( N = 50 \). For \( 1 \leq i \leq M_1 = 25 \) synapses in group \( M_1 \) we use a constant input intensity \( \lambda_1^i(t) = \nu^i \). In the remaining \( M_2 = 25 \) synapses receive a periodic intensity, \( \lambda_2^i(t) = \nu^i + \delta \nu^i \cos(\omega t) \) for \( i \in M_2 \); cf. also Sec. VA.3. Numerical parameters are \( \nu^i = 10 \text{Hz}, \delta \nu^i = 10 \text{Hz}, \) and \( \omega/(2\pi) = 40 \text{Hz} \). For the comparison of theory and simulation we need the value of \( Q \) in (18). We numerically took the Fourier transforms of \( \epsilon \) and \( W \) at the frequency \( \omega \). The time constant \( \tau_{\text{st}} \) is calculated via (29); cf. Table 1.

4. Parameters \( w_{\text{in}}, w_{\text{out}}, v_0, \) and \( \vartheta \)

We use the learning parameters \( w_{\text{in}} = \eta \) and \( w_{\text{out}} = -1.0475 \eta \), where \( \eta = 10^{-5} \). The spontaneous output rate is \( v_0 = 0 \). These values have been chosen in order to fulfill the following five conditions for learning: First, the absolute values of \( w_{\text{in}} \) and \( w_{\text{out}} \) are of the same order as the amplitude of the learning window \( W \); cf. Fig. 6. Furthermore, these absolute values are small as compared to the normalized average weight (see below). Second, the constraints on \( k_1 \) and \( k_2 \) for a stable and realizable fixed point are satisfied; cf. Sec. VB and (14). Third, the correlations in the input are weak so that \( 0 < Q \ll -k_2 \); cf. (23). This implies that the time scale \( \tau_{\text{sv}} \) of normalization in (22) is orders of magnitude smaller than the time scale \( \tau_{\text{st}} \) of structure formation in (29); cf. also Table I. Fourth, the \( k_2 \) term in (14) can be neglected in the sense of Sec. IV C. Proving this we note that the fixed point for the average weight is \( J_{\text{av}}^e = 2 \cdot 10^{-2} \) [cf. (21)] and \( k_2 = 7.04 \cdot 10^{-3} \text{s}^{-1} \). We now focus on (16). Since \( Q_{ij} \ll k_2 \) for all \( i, j \) can be neglected and \( J_t \leq \vartheta \) for all \( i \) we find from (16) the even more restrictive condition \( N^2 J_{\text{av}}^e / \vartheta > k_2 \), which is fulfilled in our parameter regime. Fifth, input and output rates are identical for normalized weights, \( \nu^i = \nu_{\text{out}} \) for \( v_0 = 0 \); see Sec. VB.

**APPENDIX C: NORMALIZATION AND CORRELATIONS BETWEEN WEIGHTS AND INPUT RATES**

The assumption of independence of the weights \( \{ J_t \} \) and the rates \( \{ \lambda^i \} \) used in Sec. VB for the derivation of a normalization property of (15) is not valid in general. During learning we expect weights to change according to their input. For the configuration of the input as introduced in Sec. VA this depends on whether synapses belong to groups \( M_1 \) or \( M_2 \). To show that even under the condition of dependence of \( \{ J_t \} \) and \( \{ \lambda^i \} \) there is a normalization property of (15) similar to that derived in Sec. VB we investigate the most extreme case in which the total mass of synaptic weight is, e.g., in \( M_2 \). Taking \( J_t = 0 \) for \( i \in M_1 \) into account we replace \( N^{-1} \sum_i J_{ij} Q_{ij} \) in (20) by \( M_2^{-1} N J_{\text{av}}^e Q_{\text{av}} \). The fixed point \( J_{\text{av}}^e \) is similar to that in (21) except for a multiplicative prefactor \( N/M_2 \) of order 1 preceding \( Q_{\text{av}} \) in (21),

\[
J_{\text{av}}^e = -k_1/|N(k_2 + Q_{\text{av}} N/M_2)|. \tag{C1}
\]

Since \( N/M_2 > 1, k_1 > 0, \) and \( k_2 + Q_{\text{av}} N/M_2 < 0, J_{\text{av}}^e \) in (21) is larger than \( J_{\text{av}}^e \) in (21), where we assumed independence of \( \{ J_t \} \) and \( \{ \lambda^i \} \). Correlations between \( \{ J_t \} \) and \( \{ \lambda^i \} \) can be neglected, however, if we assume \( 0 < Q \approx Q_{\text{av}} \ll -k_2 \); cf. (23). In this case \( J_{\text{av}}^e \) in (21) and (C1) are almost identical and independent of \( Q_{\text{av}} \).

**APPENDIX D: NORMALIZATION AND WEIGHT CONSTRAINTS**

Let us consider the influence of weight constraints (Sec. VB) on the position of the fixed point \( J_{\text{av}}^e \) in (21) and the time constant \( \tau_{\text{sv}} \) of normalization in (22). We call \( N_1 \) and \( N_2 \) the number of weights at the lower bound 0 and the upper bound \( \vartheta \), respectively. By construction we have \( N_1 + N_2 \leq N \), where \( N \) is the number of synapses.

For example, if the average weight \( J_{\text{av}}^e \) approaches \( J_{\text{av}}^e \) from below, then only \( N - N_1 \) weights can contribute to an increase of \( J_{\text{av}}^e \). For the remaining \( N_1 \) saturated synapses we have \( J_t = 0 \). Deriving from (15) an equation equivalent to (20) we obtain \( J_{\text{av}}^e = (1 - N_1/N)(k_1 + N k_2 J_{\text{av}}^e + J_{\text{av}}^e Q_{\text{av}} N/N) \). The fixed point \( J_{\text{av}}^e \) remains unchanged as compared to (21) but the time constant \( \tau_{\text{sv}} \) for an approach of \( J_{\text{av}}^e \) from below is increased by a factor \( (1 - N_1/N)^{-1} \geq 1 \) as compared to (22). Similarly, \( \tau_{\text{sv}} \) for an approach of \( J_{\text{av}}^e \) from above is increased by a factor \( (1 - N_1/N)^{-1} \geq 1 \).

The factor by which \( \tau_{\text{sv}} \) is increased is of order 1, if we use the upper bound \( \vartheta = (1 + d) J_{\text{av}}^e \), where \( d > 0 \) is of order 1. If \( J_{\text{av}}^e = J_{\text{av}}^e \), at most \( N_1 = N/(1 + d) \) synapses can saturate at the upper bound comprising the total weight. The remaining \( N_2 = N - N/(1 + d) \) synapses are at the lower bound 0. The time constant \( \tau_{\text{sv}} \) is enhanced by at most \( 1 + 1/d \) and \( 1 + d \) for an approach of the fixed point from below and above, respectively.

**APPENDIX E: RANDOM WALK OF SYNAPTIC WEIGHTS**

We consider the random walk of a synaptic weight \( J_t(t) \) for \( t > t_0 \), where \( J_t(t_0) \) is some starting value. The time course of \( J_t(t) \) follows from Eq. (1).
For a specific time; see Fig. 2 (bottom). According to (E1) an input can be prescribed whereas instance (7). For large as defined in Sec. II C. Finally, it may be well to realize on line of (E1) and extend the integration over the new time by a constant amount randomly variable step size. Suitable rescaling of this can be positive or negative. The learning window \( W \) we obtain a random walk with independent steps but variable spike at time \( \tau \). As in Sec. II B we substitute \( \tau \) for arbitrary times and a variable amount \( \tau - \tau' \). We introduce a big error for \( \tau \neq \tau' \). In this case we therefore have \( \langle S_i(t) S_i(t') \rangle = \nu_i \nu_i^{\text{in}} \). For arbitrary times \( \tau ' \) we find (cf. App. A)

\[
\langle S_i(t) S_i(t') \rangle = \nu_i \nu_i^{\text{in}} + \delta(\tau - \tau').
\]

Similarly, for the correlation between output spike trains we obtain

\[
\langle S^\text{out}(t') S^\text{out}(t') \rangle = \nu^\text{out} \nu^\text{out} + \delta(\tau' - \tau').
\]

Using (E5), (E6), and (E7) in (E4), performing the integrations, and inserting the outcome together with (E3) into (E2) we arrive at

\[
\text{Var} J_i(t) = (t - t_0) D
\]

To simplify the ensuing argument, upper and lower bounds for each weight are not taken into account.

For the calculation of the variance in (E2) we first of all consider the term \( \langle J_i \rangle \). We use the notation \( \langle S^\text{in}(t) \rangle = \nu^\text{in} \) and \( \langle S^\text{out}(t) \rangle = \nu^\text{out} \) because of constant input and output intensities. Stochastic independence of input and output leads to \( \langle S^\text{in}(t') S^\text{out}(t') \rangle = \nu^\text{in} \nu^\text{out} \). Using (E1) and \( \int d W(s) = \bar{W}(0) \) we then obtain

\[
\langle J_i \rangle = J_i(t_0) + (t - t_0) \left( \nu_i \nu_i^{\text{in}} + \nu_i \nu_i^{\text{out}} \bar{W}(0) \right).
\]

Next, we consider the term \( \langle J_i^2 \rangle \) in (E2). Using (E1) once again we obtain for \( t - t_0 \gg W \)

\[
\langle J_i^2 \rangle = -J_i(t_0)^2 + 2J_i(t_0) \langle J_i \rangle + \int_{t_0}^{t} dt' \int_{t_0}^{t} dt'' W(t'' - t') S^\text{in}(t') S^\text{out}(t')
\]

\[
\times \left\{ \langle S^\text{in}(t') S^\text{in}(t') \rangle (\nu_i^{\text{in}})^2 + \langle S^\text{out}(t') S^\text{out}(t') \rangle \right\} + 2 \int d s W(s) \left\{ \langle S^\text{in}(t') S^\text{in}(t' + s) S^\text{out}(t') \rangle \right\} + \int d s \int d W(s) W(v) \left\{ \langle S^\text{in}(t') S^\text{in}(t' + s) \rangle \right\}.
\]

Since input and output were assumed to be independent, we get

\[
\langle S^\text{in}(t') S^\text{in}(t') \rangle = \langle S^\text{in}(t') \rangle \langle S^\text{in}(t') \rangle = \nu_i^{\text{in}} \langle S^\text{in}(t') \rangle = \nu_i^{\text{in}} \nu_i^{\text{in}}.
\]

We note that \( \langle S^\text{in}(t') \rangle = \nu_i^{\text{in}} \) for all \( i \) and \( \langle S^\text{out}(t') \rangle = \nu_i^{\text{out}} \).

Input spikes at times \( t' \) and \( t'' \) are independent as long as \( t' \neq t'' \). In this case we therefore have \( \langle S^\text{in}(t') S^\text{in}(t') \rangle = \nu_i^{\text{in}} \nu_i^{\text{in}} \). For arbitrary times \( t' \) and \( t'' \) we find (cf. App. A)

\[
\langle S^\text{in}(t') S^\text{in}(t') \rangle = \nu_i^{\text{in}} \nu_i^{\text{in}} + \delta(t' - t'').
\]

Similarly, for the correlation between output spike trains we obtain

\[
\langle S^\text{out}(t') S^\text{out}(t') \rangle = \nu_i^{\text{out}} \nu_i^{\text{out}} + \delta(t' - t'').
\]

Using (E5), (E6), and (E7) in (E4), performing the integrations, and inserting the outcome together with (E3) into (E2) we arrive at

\[
\text{Var} J_i(t) = (t - t_0) D
\]

where

\[
D = \nu_i^{\text{in}}(w_i^{\text{in}})^2 + \nu_i^{\text{out}}(w_i^{\text{out}})^2 + \nu_i \nu_i^{\text{out}} \bar{W}(0) \left[ 2(w_i^{\text{in}} + w_i^{\text{out}}) + \bar{W}(0) (\nu_i^{\text{in}} + \nu_i^{\text{out}}) \right].
\]

as announced.
TABLE I. Values of the parameters used for the numerical simulations (first part) and derived quantities (second part).

<table>
<thead>
<tr>
<th>Parameters</th>
<th>( \eta = 10^{-2} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>( w^m = \eta )</td>
<td></td>
</tr>
<tr>
<td>( w^{mot} = -1.0475 \eta )</td>
<td></td>
</tr>
<tr>
<td>( A_+ = 1 )</td>
<td></td>
</tr>
<tr>
<td>( A_- = -1 )</td>
<td></td>
</tr>
<tr>
<td>( \tau_+ = 1 \text{ms} )</td>
<td></td>
</tr>
<tr>
<td>( \tau_- = 20 \text{ms} )</td>
<td></td>
</tr>
<tr>
<td>( \delta \theta^{av} = 4 \times 10^{-1} )</td>
<td></td>
</tr>
<tr>
<td>( \omega/(2\pi) = 40 \text{s}^{-1} )</td>
<td></td>
</tr>
<tr>
<td>Further parameters</td>
<td>( \nu_0 = 0 )</td>
</tr>
<tr>
<td>( \theta = 0.1 )</td>
<td></td>
</tr>
</tbody>
</table>

| Derived quantities | \( W(0) := \int ds W(s) = 4.75 \times 10^{-8} \text{s} \) |
| | \( \int ds W(s)^2 = 3.68 \times 10^{-12} \text{s} \) |
| | \( \int ds W(s) e^{(-s)} = 7.04 \times 10^{-6} \) |
| | \( Q = 6.84 \times 10^{-7} \text{s}^{-1} \) |
| | \( k_1 = 1.9 \times 10^{-4} \text{s}^{-1} \) |
| | \( k_2 = 1.0 \times 10^{-4} \text{s}^{-1} \) |
| | \( k_3 = 7.04 \times 10^{-5} \text{s}^{-1} \) |
| | \( \alpha = 2.10^4 \text{s}^{-1} \) |
| | \( \tau^{max} = 2.93 \times 10^4 \text{s}^{-1} \) |
| | \( \tau^{min} = 1.62 \times 10^5 \text{s}^{-1} \) |
| | \( \alpha = 2.10^{-2} \) |
| | \( D = 2.47 \times 10^{-9} \text{s}^{-1} \) |
| | \( D' = 1.47 \times 10^{-9} \text{s}^{-1} \) |

References:
